

# **ELECTION METHODOLOGIES**

## **FML PROJECT 2016**

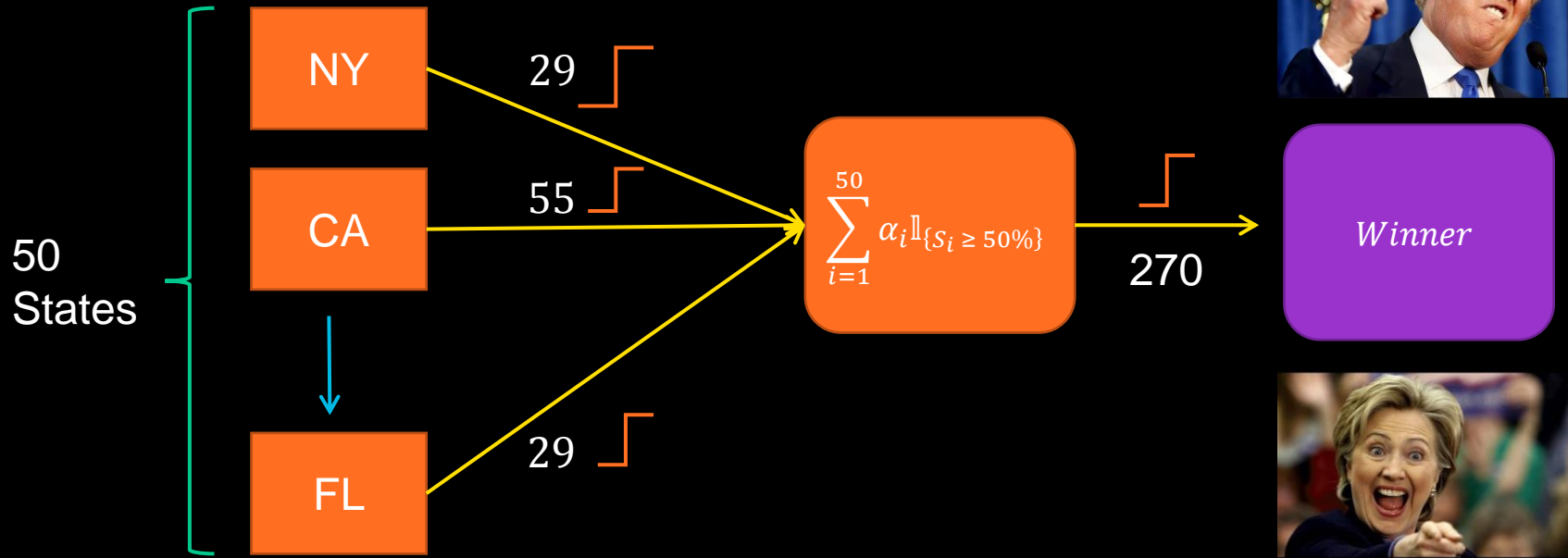
Dhruv Madeka

# TOPICS

- Modeling the Election
- Forecaster Evaluation – Ex-Post
- Forecaster Evaluation – Ex-Ante
- Online Learning of Forecasters

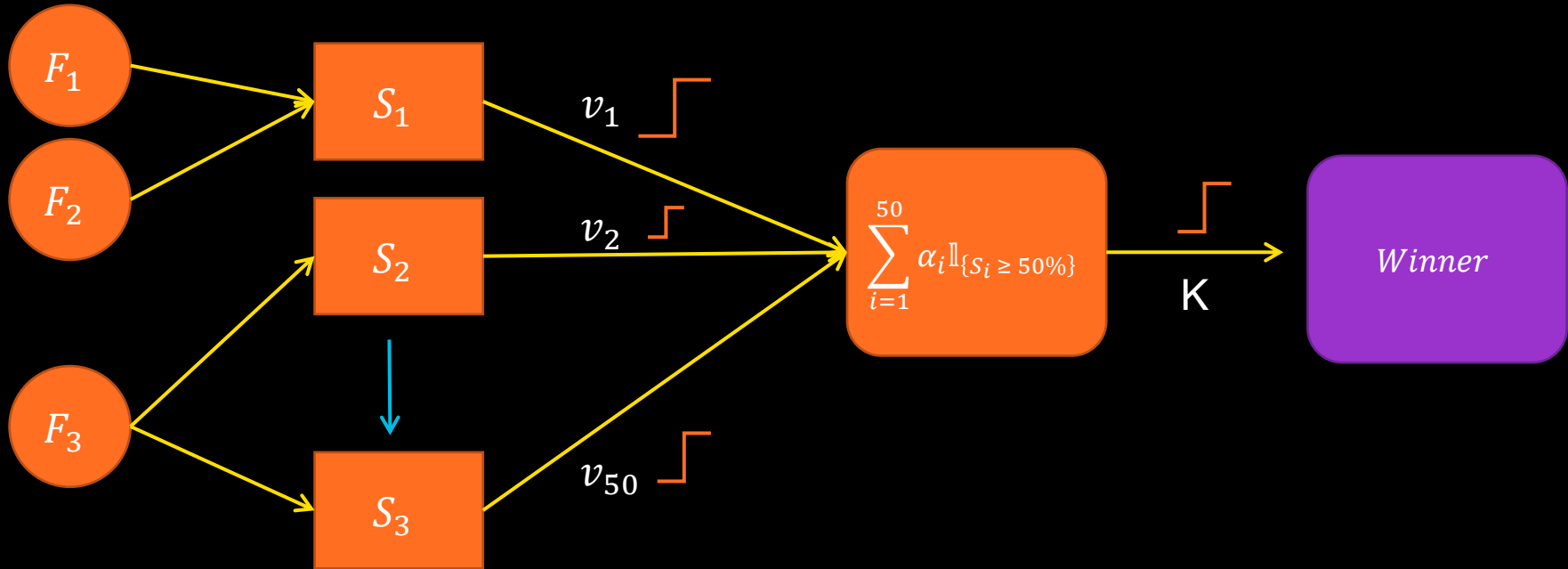
# PRESIDENTIAL MECHANICS

In the US, the Presidential Election isn't decided by the popular vote but rather by the total number of Electoral College Votes.



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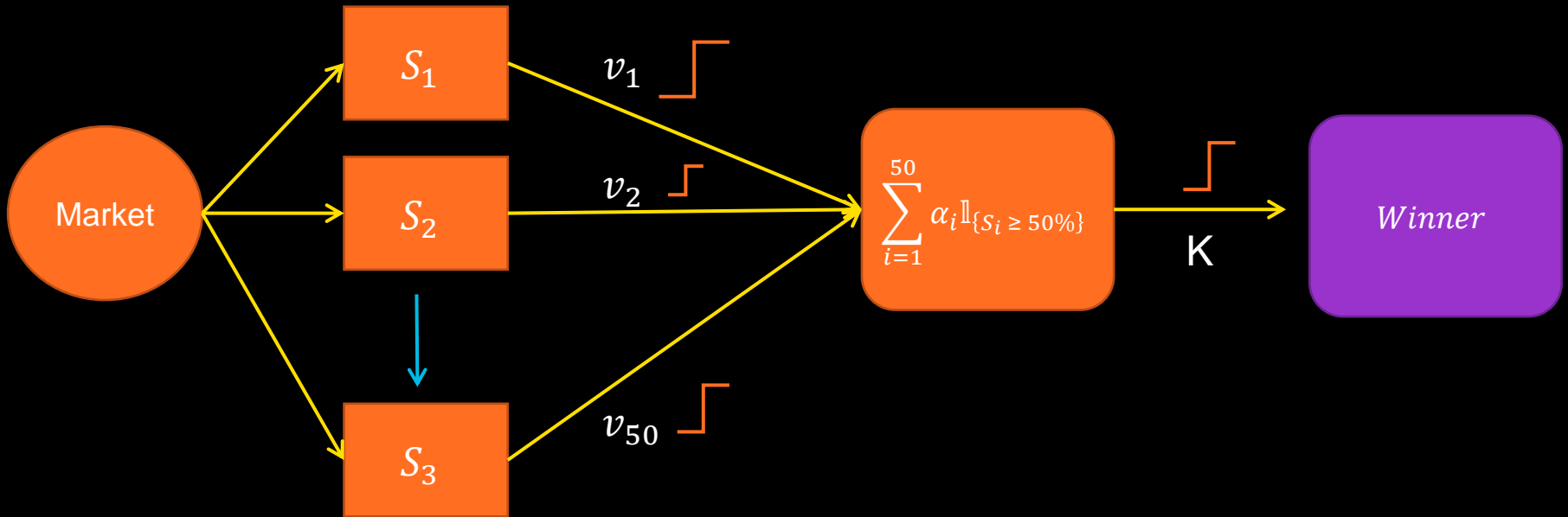


# CAPM MODEL

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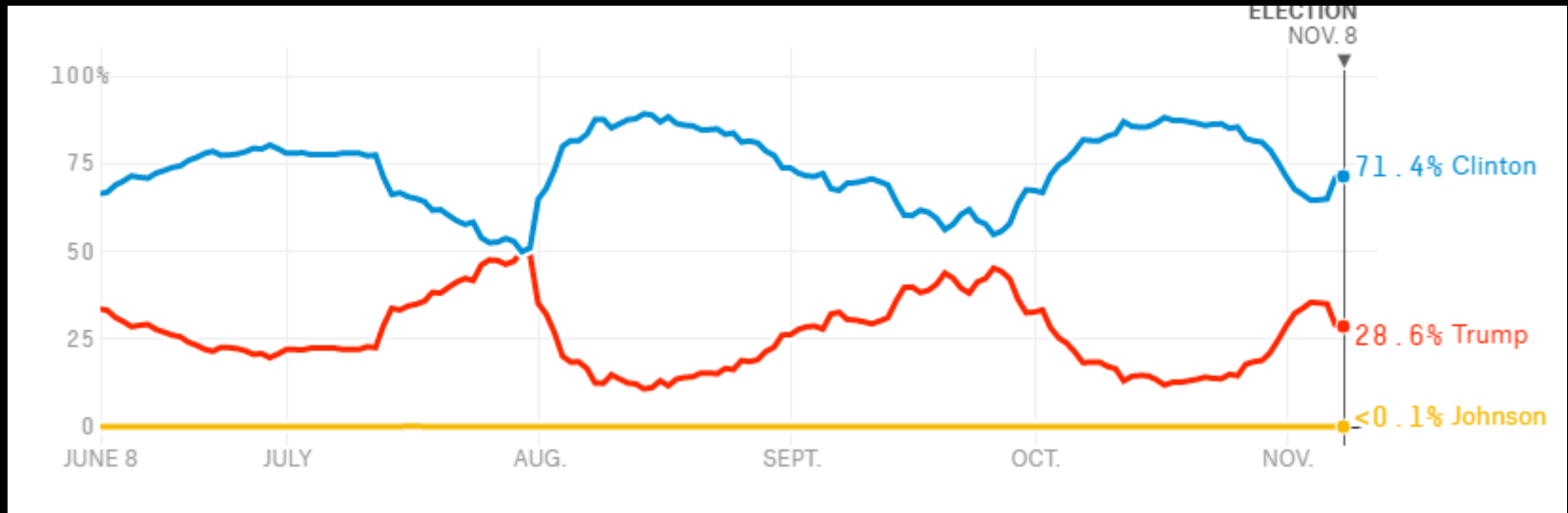
# PRESIDENTIAL MECHANICS

In the US, the Presidential Election isn't decided by the popular vote but rather by the total number of Electoral College Votes.



# MODELLING ISSUES

- Not enough noise! If you truly believe probabilities move this much (uncertainty is very high) then the reported probability should be 50%



# CAPM MODEL

- Each state is a stock, the popular vote is the Market
- Assume each state evolves like:

$$S_t^i = \alpha^i + \beta^i M_t + \epsilon^i$$

- Assume Market follows a Bachelier Process:

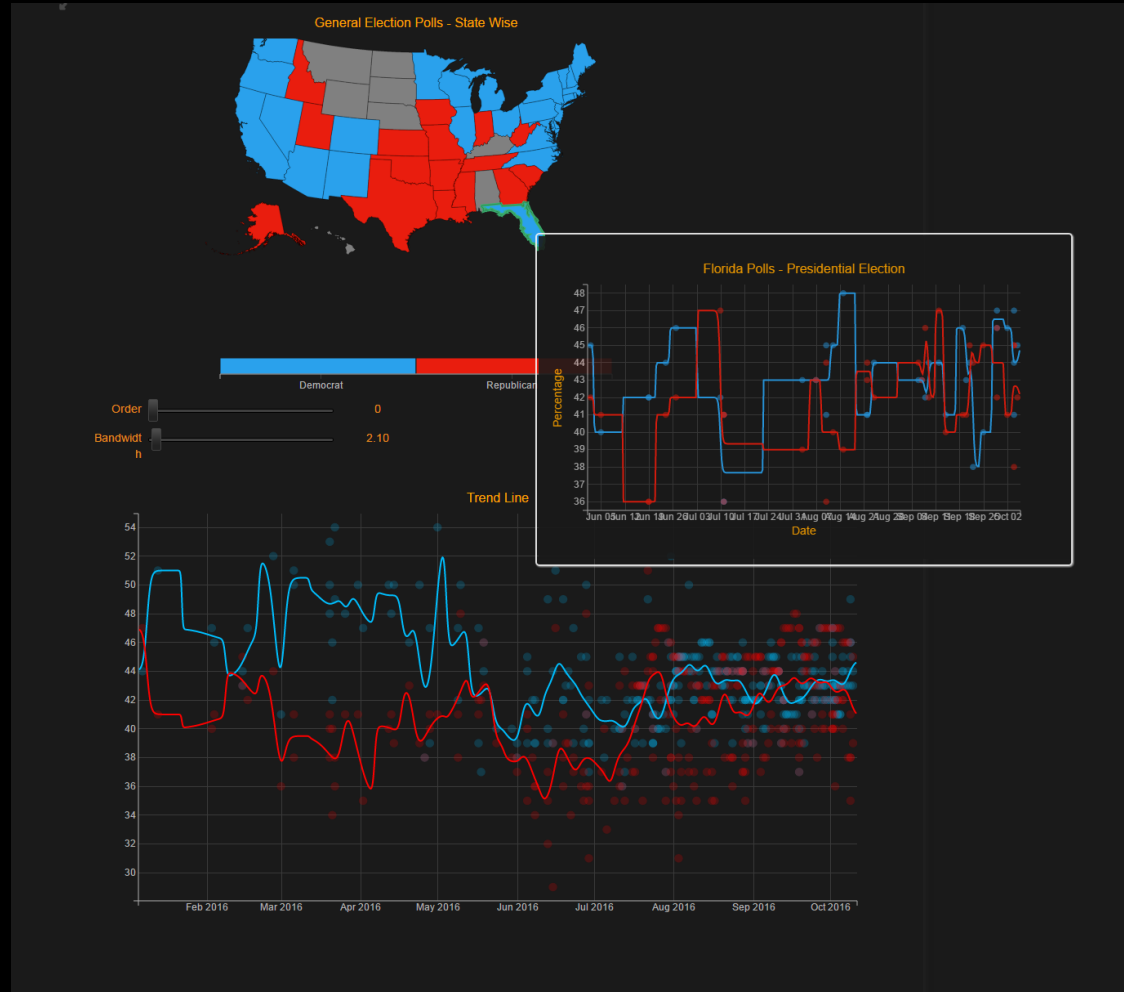
$$dM_t = \sigma^m dW_t$$

- Calibrate to polling data (Source: RealClearPolitics)



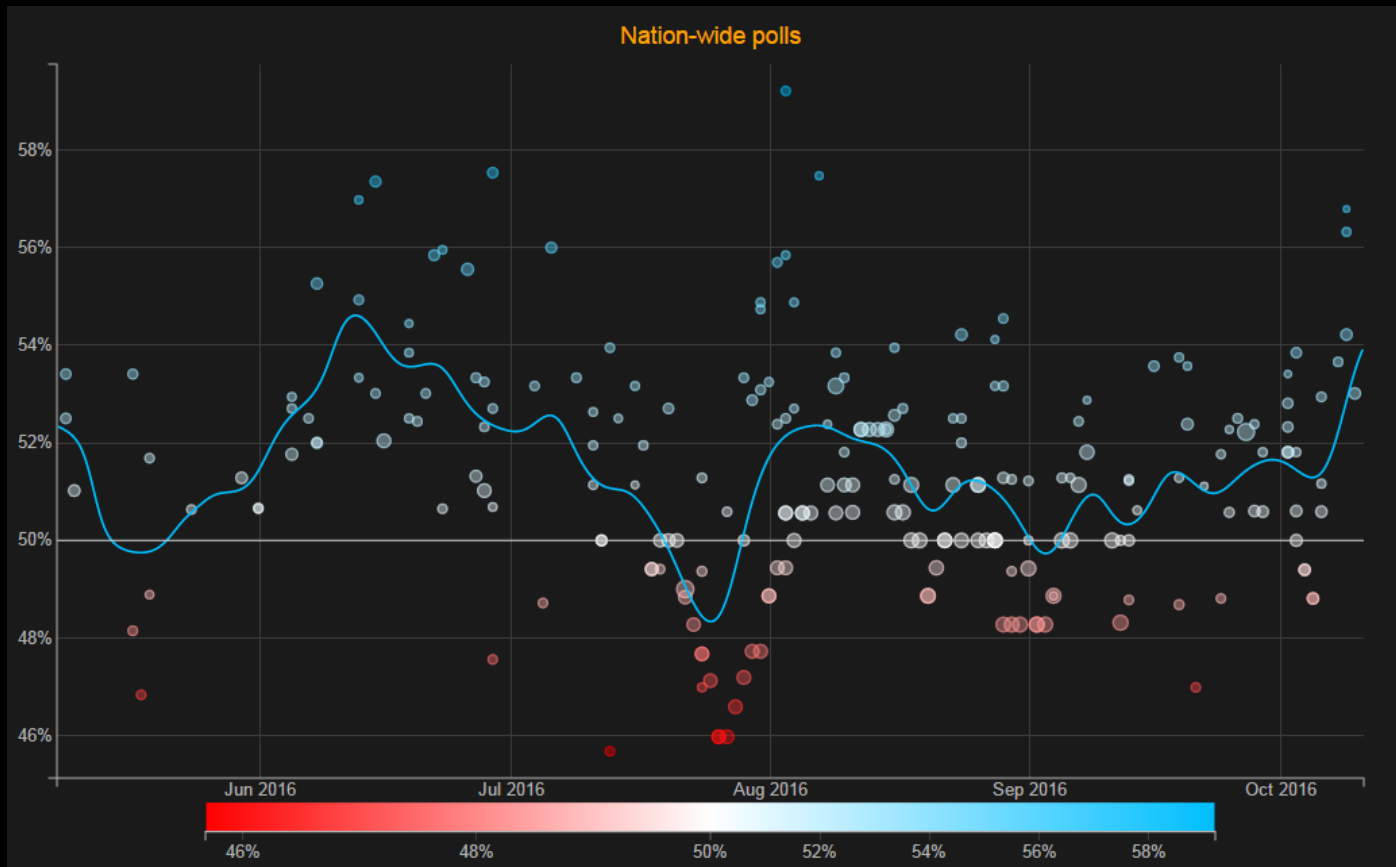
# CALIBRATION

- Calibrate  $M$  to national polls
- Calibrate  $S$  to state polls



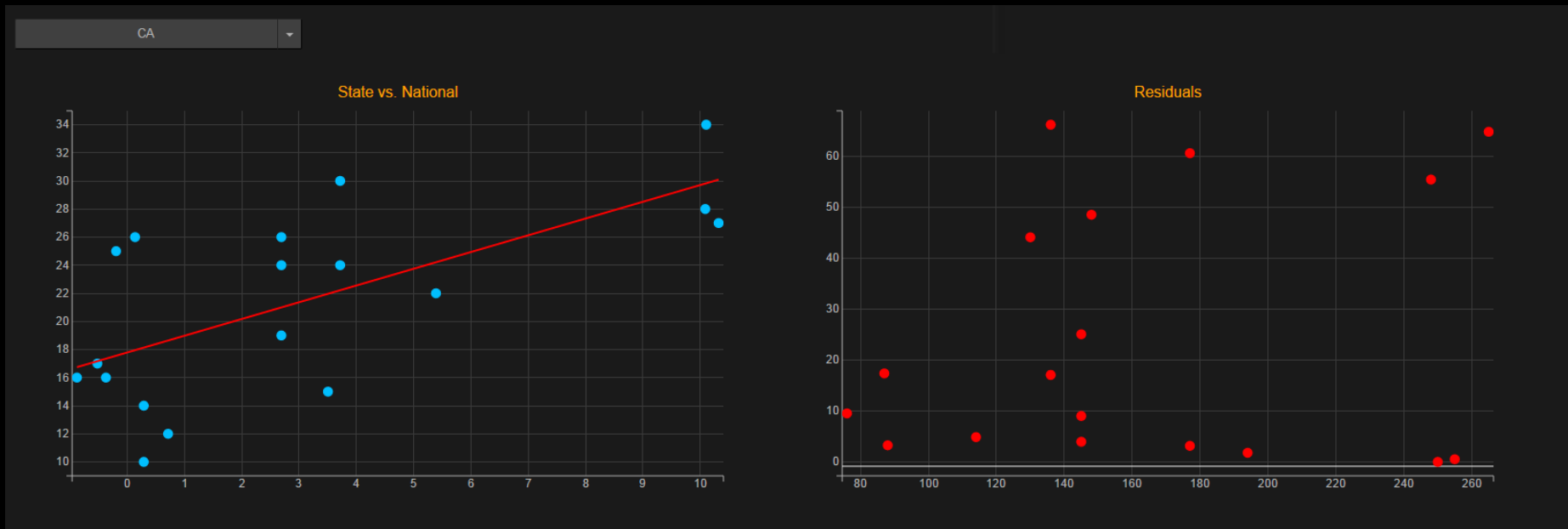
# CALIBRATION

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- Calibrate M to national polls
- Calibrate S to state polls



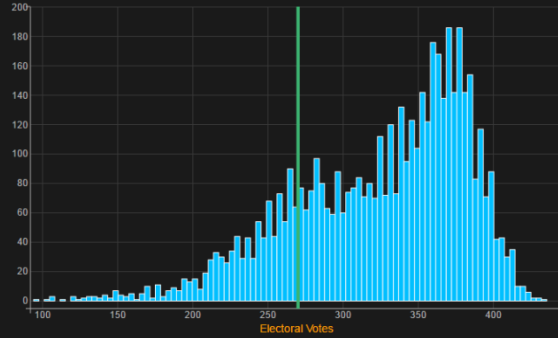
# FINAL STEP: SIMULATE

Market Volatility: 26.80  
Number of Simulations: 5000

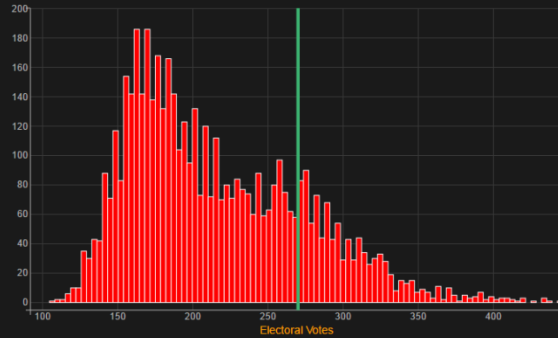
Go

Clinton won 81.12% of the time

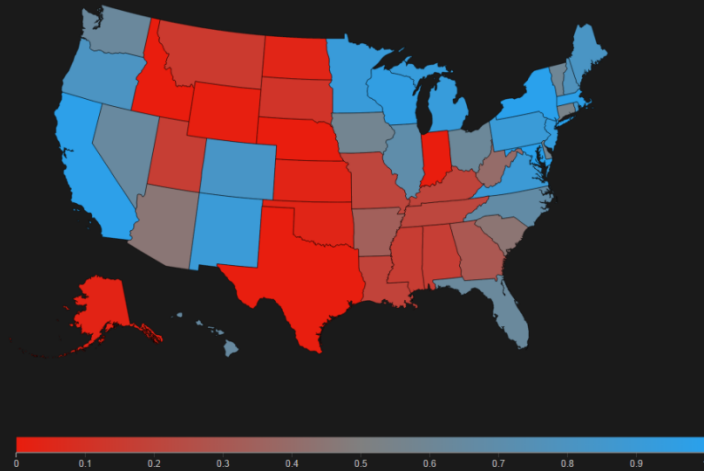
Clinton Simulations



Trump Simulations



Simulation Results - State Wise

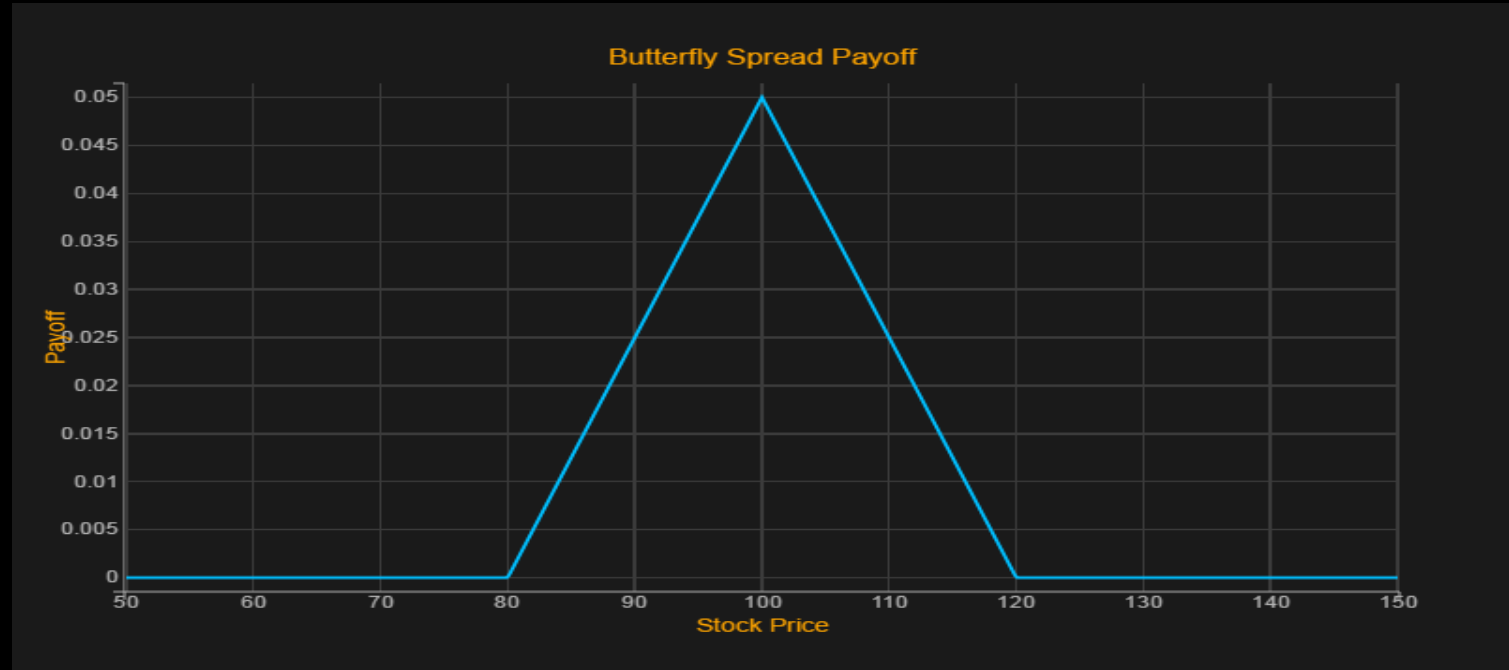


# OPTION MODEL

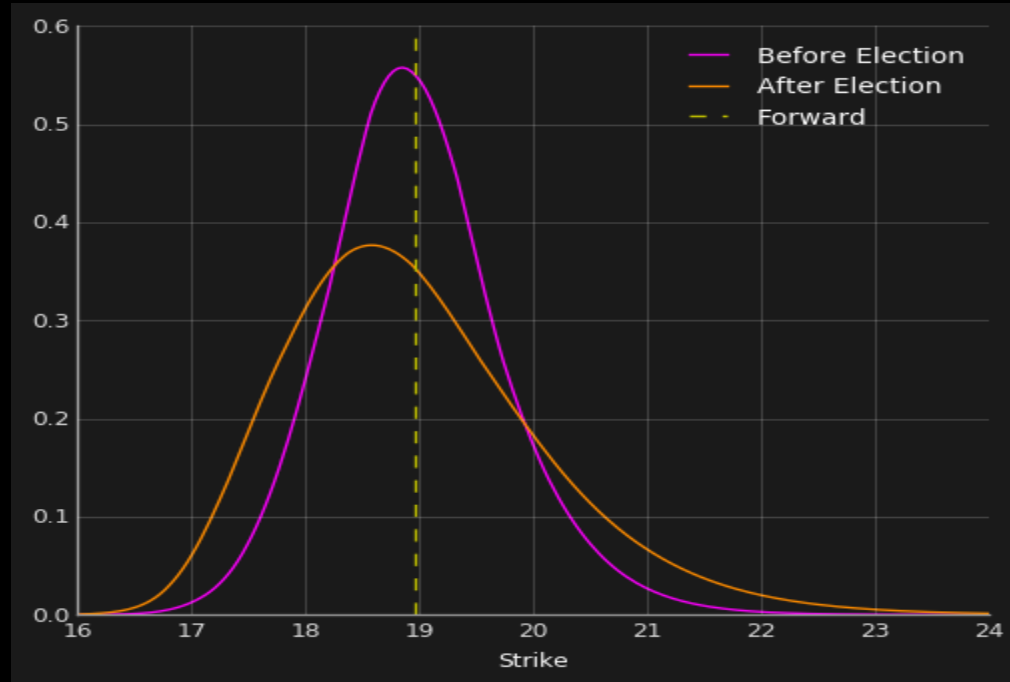
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# RISK NEUTRAL DENSITY (NO RATES)

Butterfly Spread: ( $\varepsilon > 0$ ) 
$$\frac{C(K-\varepsilon) - 2C(K) + C(K+\varepsilon)}{\varepsilon^2}$$



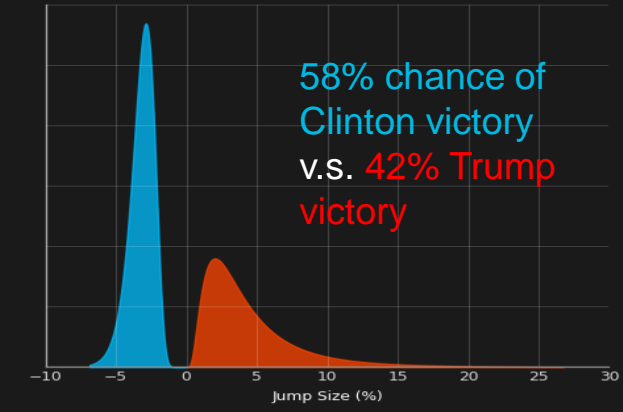
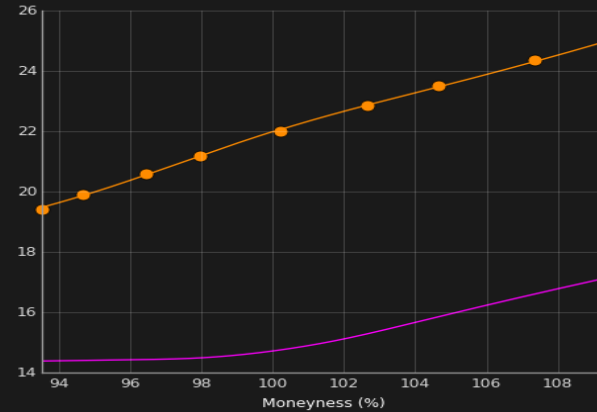
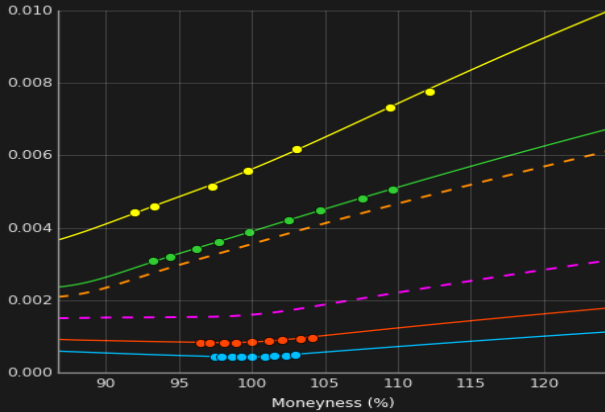
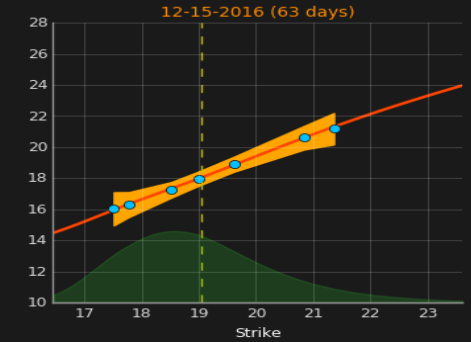
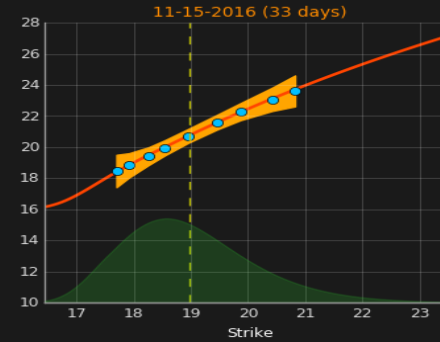
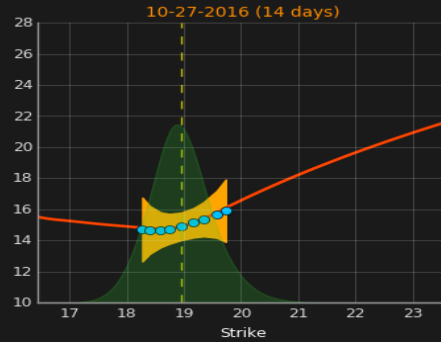
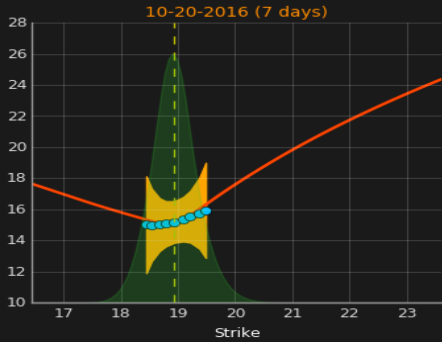
# OPTION MARKET ANALYSIS



As of Date: Oct 13, 2016

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# OTHER MODELS

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# ROBUST CALIBRATION OF S

- Calibrate S to state polls

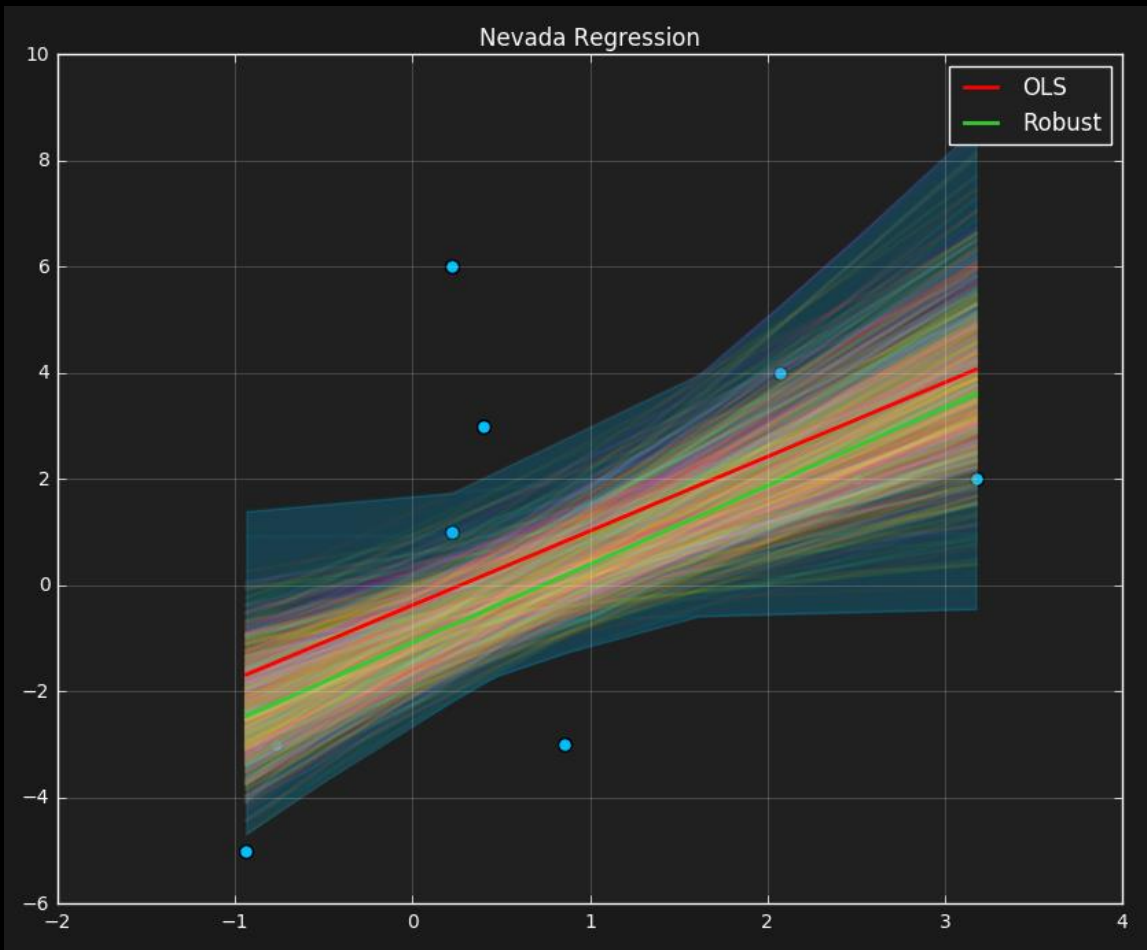
$$\alpha^i \sim N(\alpha^{OLS}, \sigma^\alpha)$$

$$\beta^i \sim N(\beta^{OLS}, \sigma^\beta)$$

$$\sigma^i \sim |N(0, \epsilon^i)|$$

$$\mu^i = \alpha^i + \beta^i M_T$$

$$S_T^i \sim StudentT(\mu^i, \sigma^i, \nu = 3)$$



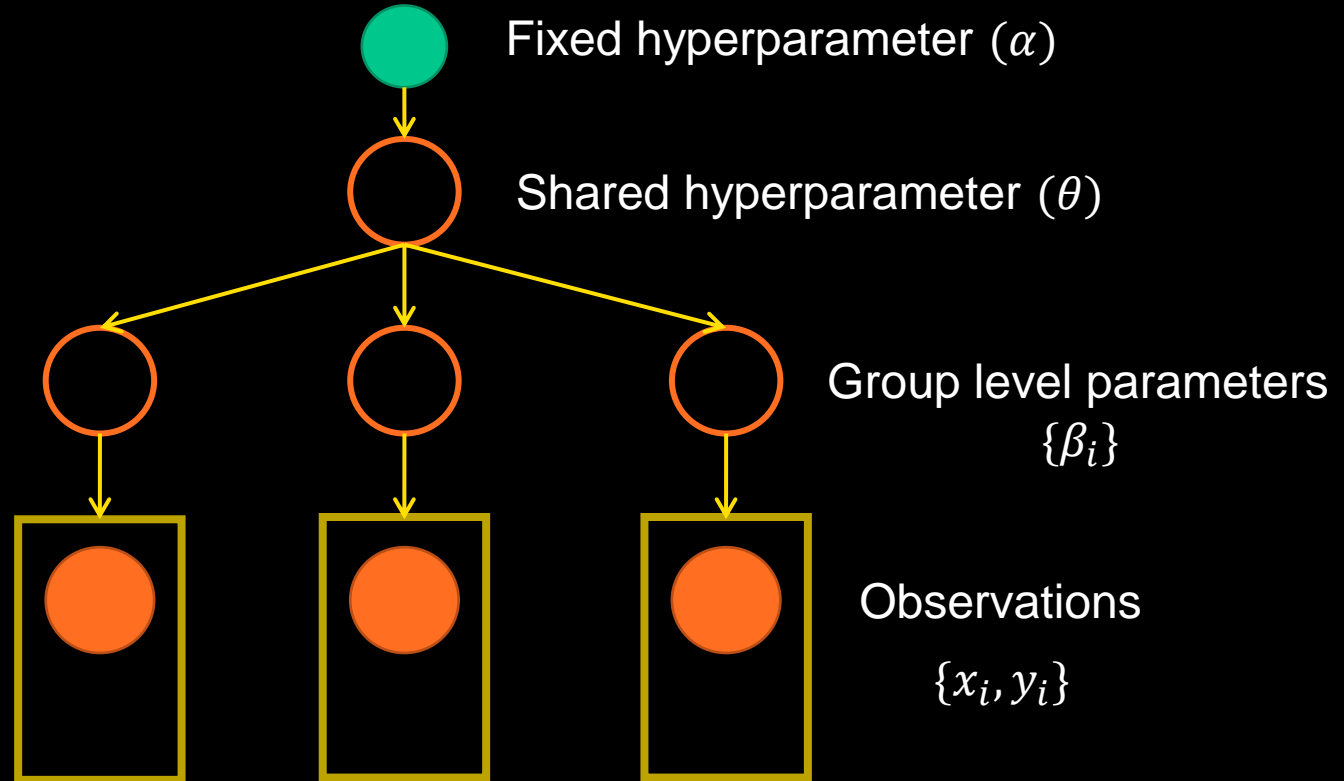


# HIERARCHICAL MODEL

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# FACTORIZING IN JOINT DYNAMICS

- Hierarchical Regression to incorporate joint dynamics between states



# COMPARING FORECASTERS

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# WHO WAS BETTER?

- In general, given a sequence of forecasts and a single (or multiple realizations, how do we evaluate efficacy?
- Consider a canonical probability space endowed with a filtration
- 

$$(\Omega, \mathcal{F})$$

$\mathcal{P} \sim \text{Class of Prob. Measures}$

- Scoring Rules: Map Probability Measure and Realized Event to Real Number

$$S: \Omega \times \mathcal{P} \rightarrow \bar{\mathbb{R}}$$

- What's the issue with using any function (like say  $p(\omega)$ )?

# PROPER SCORING FUNCTIONS

- Scoring function should incentivize scorer to publicize his **true** probability. This means that:

$$\max_q \mathbb{E}^{\mathbb{P}}[S(\omega, q)] = p$$

It is strictly proper if  $p$  is the unique maximizer (since a constant scoring function which assigns 1 to all events is technically proper).



# WHO WAS BETTER?

There are many ways to compare forecasters:

- Brier Score

$$\text{Brier Score} = \sum_{t=1}^T (p_i - o_i)^2$$

- Lower score is better
- Proper (Honest Scoring Rule)

# CONNECTION TO MACHINE LEARNING

Condition for a proper scoring function:

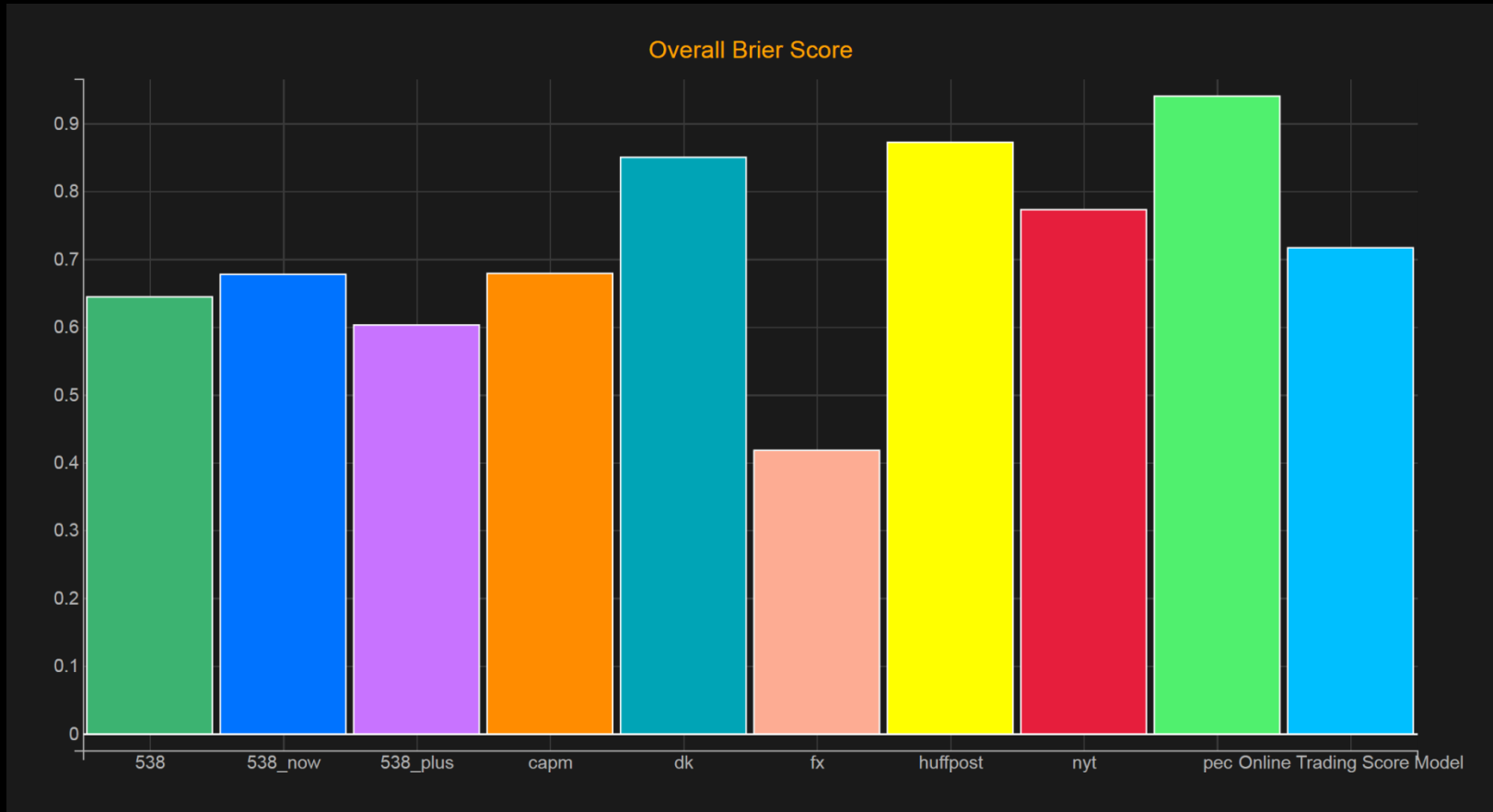
$$\operatorname{argmin}_q \mathbb{E}^{\mathbb{P}}[S(\omega, q)] = \mathbb{E}^{\mathbb{P}}[\omega]$$

imply (with some regularity conditions [1] that  $S(x, y) = D_{\phi}(x, y)$  for some convex, differentiable function  $\phi: \mathbb{R} \rightarrow \mathbb{R}$

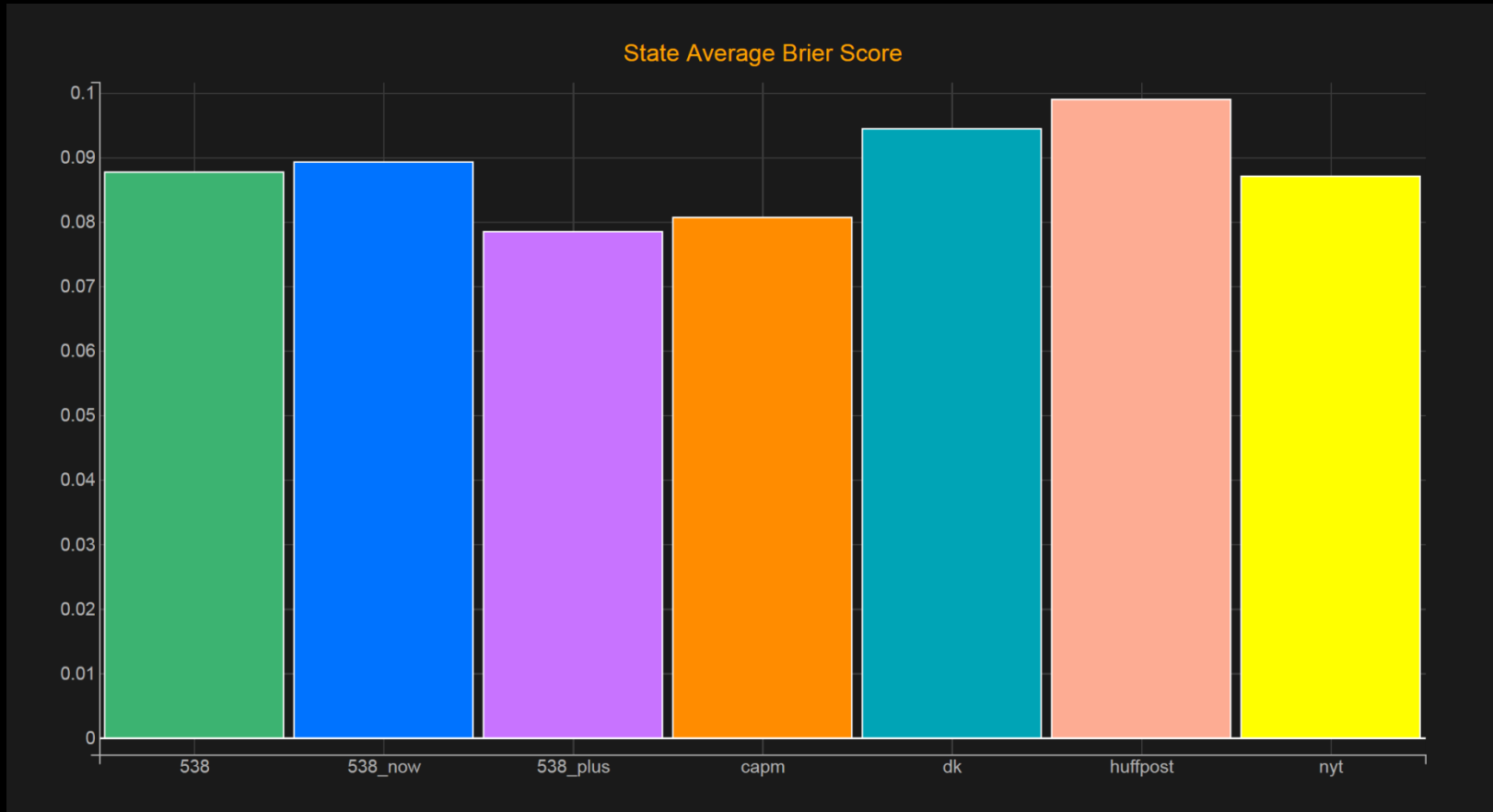
$$D_{\phi}(x, y) = \phi(x) - \phi(y) - \phi'(y)(x - y)$$

Proper Scoring Functions  $\leftrightarrow$  Bregman Divergences

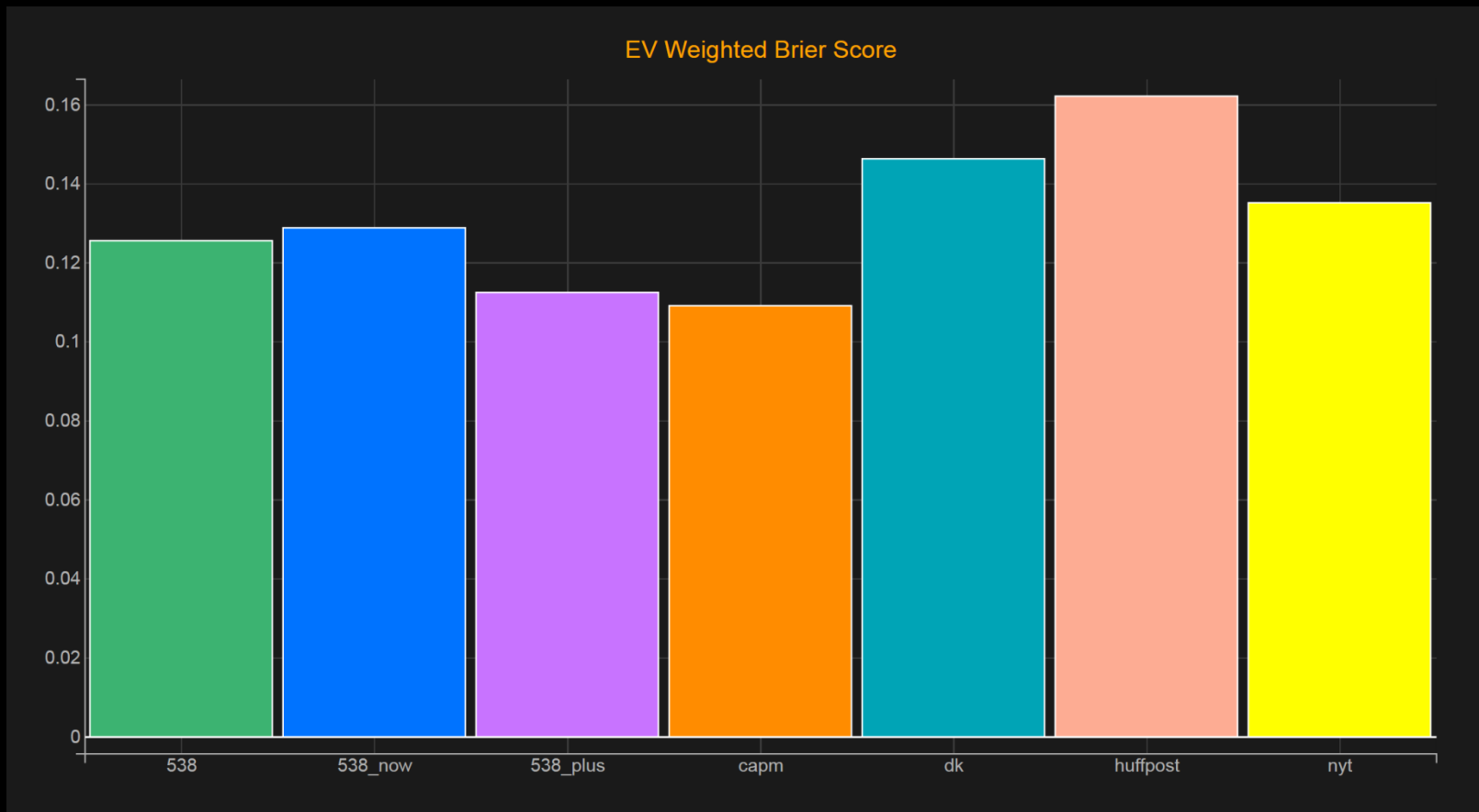
# BRIER SCORES



# BRIER SCORES – STATEWISE AVERAGE



# BRIER SCORES – EV WEIGHTED AVERAGE



# WHO WAS BETTER?

There are many ways to compare forecasters:

- Log Likelihood

Imagine we were trying to forecast rain or not every month.

- True Probability  $\rightarrow \frac{1}{10}$
- Forecaster A  $\rightarrow \frac{1}{4}$
- Forecaster B  $\rightarrow 0$

# SILVER VS WANG 2016

## Chance of winning



Hillary Clinton

71.4%

Donald Trump

28.6%



## Not 100%

*November 3rd, 2016, 4:55am by Sam Wang*

For a moment this morning, the top banner probability has read 100%. Sorry, rounding glitch in the software. It should max out at >99%. Fixing soon.

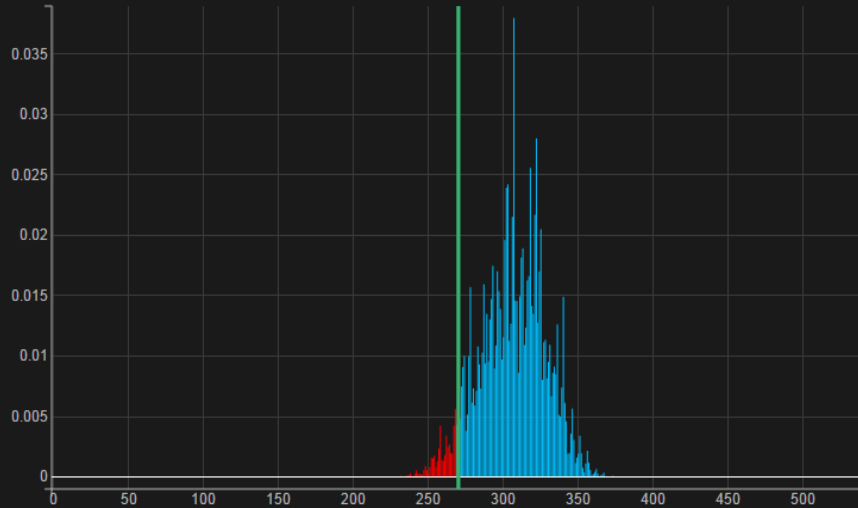
What if Clinton had won in a landslide? Who would have been better?

# SILVER VS WANG 2016

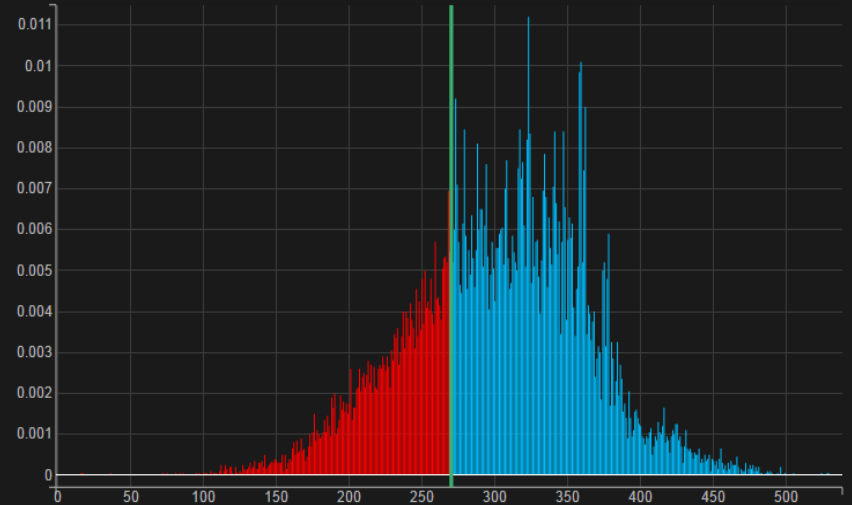
What if Clinton had won in a landslide? Who would have been better?

Nate Silver

PEC Histogram of Electoral Votes



538 Histogram of Electoral Votes

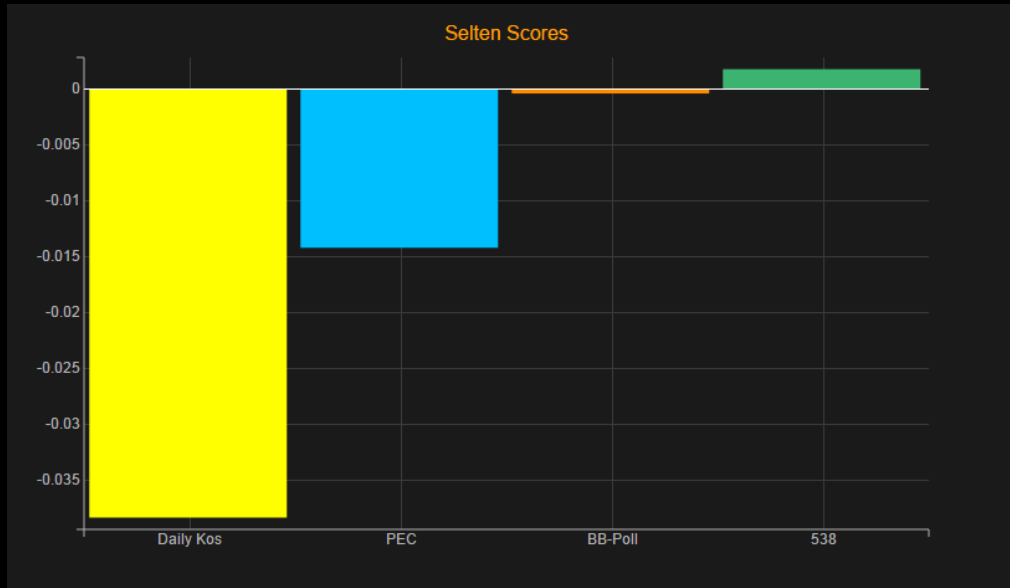




# WHO WAS BETTER?

There are many ways to compare forecasters:

- Selten Score – Compute Brier Score for each bin of the Histogram

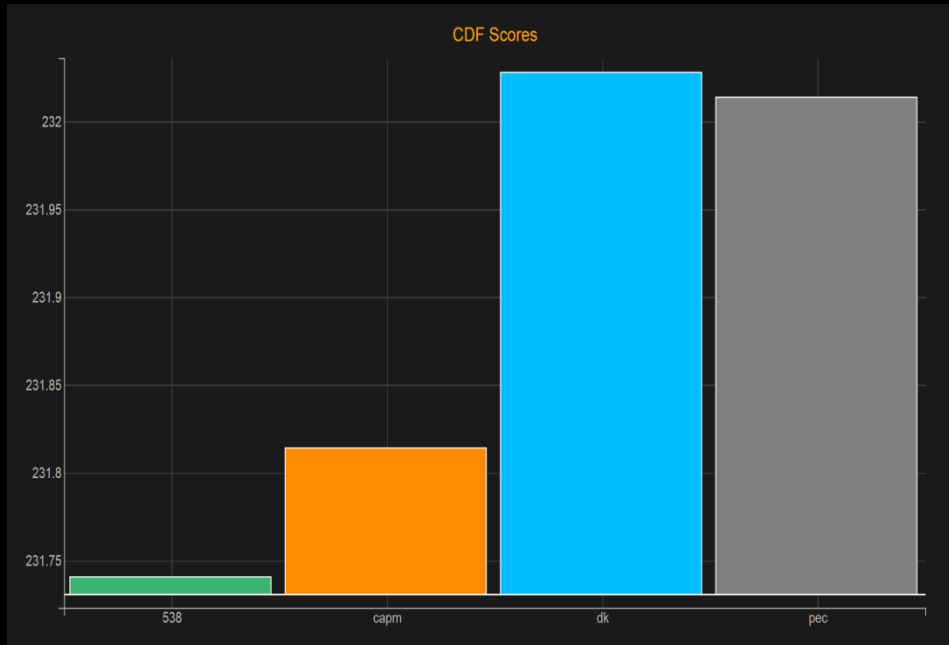


$$Selten = 2p_i^* - \sum_{i=1}^N p_i^2$$

- Proper (Honest Scoring Rule)
- Highest value is best
- Does not take into account topology of bins

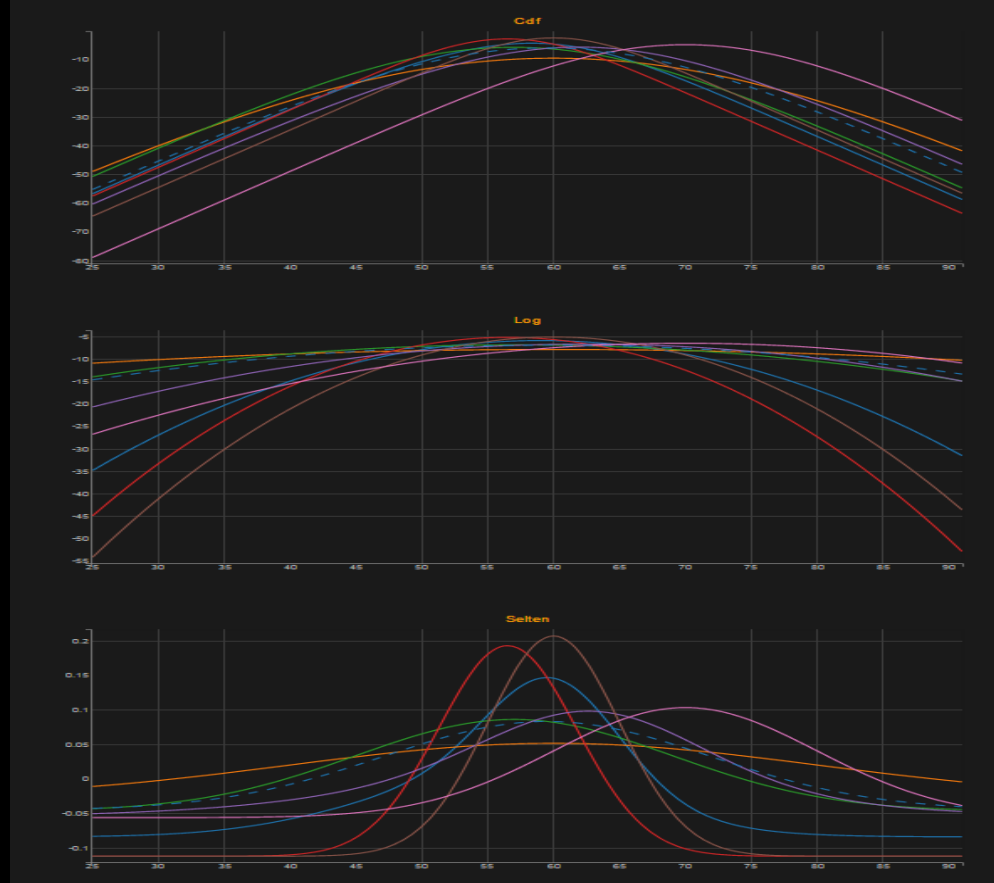
# WHO WAS BETTER?

Selten has no notion of the topology of bins. Guessing 302 EV, when the result was 303 EV is no different from guessing 538 EV. We present the CDF score which factor this into the scoring function, by taking the Brier at each level for the CDF.



$$CDF\ Score = \sum (F(x) - 1_{\{x \geq \omega\}})^2$$

# WHO WAS BETTER?

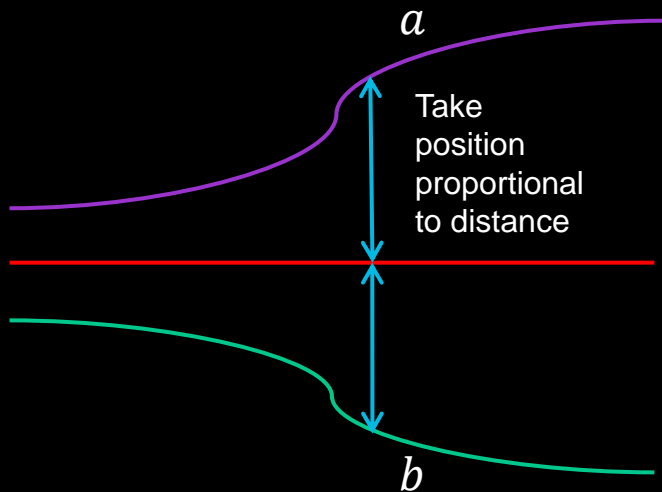


# WHO WAS BETTER?

There are many ways to compare forecasters:

- All these are ex-post judgements. How can we decide who is better before the event? (or how do we perform online learning on forecasters)
- Take position at time  $t$  proportional to their distance from  $mid_t$  or the betting market – Settle at realization
- Compute P&L of the holdings at current mid
- Proper Scoring Rule
- Best P&L so far is best guess of best forecaster

# TRADING SCORE



Position at time  $t$ :  $(a_t - b_t)$

$$\text{Price: } \frac{a_t + b_t}{2}$$

2 Date, 1 Period Model:

$$PNL(T) = 1_{\{\omega\}}(a_0 - b_0) + \frac{a_0^2 - b_0^2}{2}$$

$$\Rightarrow \operatorname{argmax}_{a_0} PNL(T) = \mathbb{E}^{\mathbb{P}}[1_{\{\omega\}}]$$

# COMBINING FORECASTERS

Minimize regret:

$$\text{Regret}(T) := \sum_{t=1}^T L(\hat{y}_t, y_t) - \min_i \sum_{t=1}^T L(\hat{y}_{t,i}, y_t)$$

Weight Update:

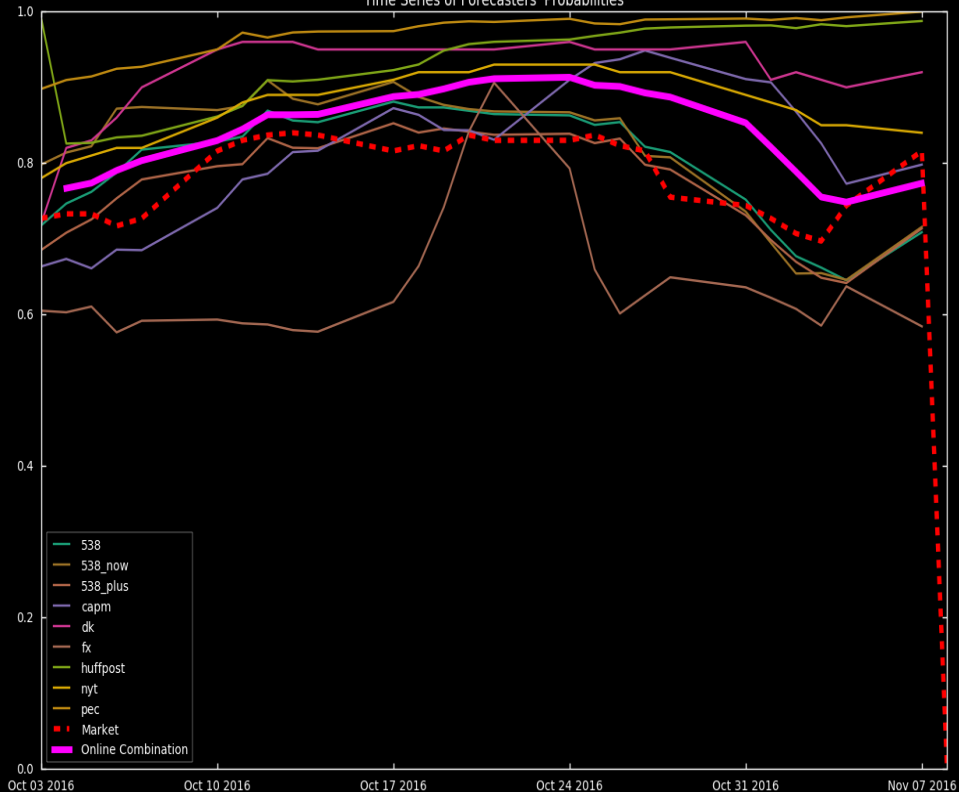
$$w_{t+1,i} \leftarrow w_{t,i} e^{-\eta L(\hat{y}_{t,i}, y_t)}$$

Prediction:

$$\hat{y}_t = \frac{\sum_{i=1}^N w_{t,i} y_{t,i}}{\sum_{i=1}^N w_{t,i}}$$

# PREDICTION AND P&L

Time Series of Forecasters' Probabilities



Profit and Loss Graph

